



MAHSA
UNIVERSITY

KINEMATICS OF ROBOTICS (KOR)

23rd October 2019
Wednesday
1.00pm - 5.00pm
Lvl 2, DLT 22201, Humanity Building
MAHSA University

WHO SHOULD ATTEND

Bachelor, Masters and PhD students, robotics engineers, robotics and automation lecturers, pupils, teachers and other professionals.

This talk aims to share, discuss and spread knowledge of the most recent theories, issues and practices among academicians and practitioners in the robotics arena that relate to NAO humanoid robot-walking kinematics. Our goal is to support and encourage the speaker to share his knowledge and the publications of his research work in humanoid robot-walking which will ultimately contribute to the development of science and technology.

FEES

MAHSA STUDENTS	RM50
MAHSA STAFF	RM100
OTHER STUDENTS	RM80
OTHERS	RM150

SPEAKER



**PROF. DR HANAFIAH
BIN YUSSOF**

Director of the Institute of
Mechanical Engineering and
Technology Advancement
(I-META)
Faculty of Mechanical
Engineering, UTM

Professor Dr Hanafiah Yussof is a Professor in the Faculty of Mechanical Engineering at Universiti Teknologi MARA (UiTM). He received his B. Eng degree in Mechanical Engineering from Iwate University, Japan, in 1998; his M. Eng degree in Mechanical Systems Engineering from Yamagata University, Japan, in 2005; and his PhD in Information Science from Nagoya University, Japan, in 2008. His research interests include humanoid robotics, medical and rehabilitation robotics, grasping and manipulation of robotic hands, tactile sensors, bio-sensors, sensor fusion, military robotics, and intelligent control of mobile manipulators. Professor Dr Hanafiah has contributed more than a hundred publications in international journals, books, book chapters, conference proceedings, newspapers and magazines. He is the editor of the book "Robot Localization and Map Building", published by In-Tech Press, Vienna, in 2010.



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